

Multi-objective Dynamic Aperture Optimization for NSLS-II Ring



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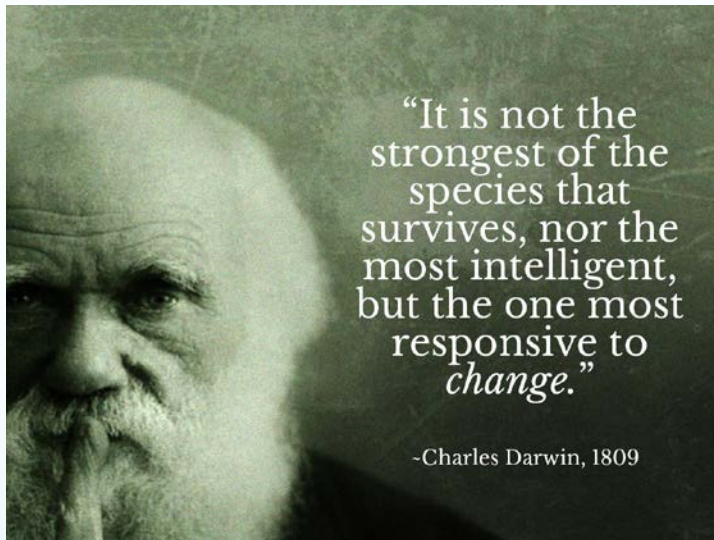
IAS program on HEP Conference 2016, Hong Kong

Outline

- Multi-objective genetic algorithm (MOGA)
- Existing optimizations on dynamic aperture
- New efficient method with MOGA
- Applications on NSLS-II storage ring
- Correlation between nonlinear driving terms and dynamic aperture

Genetic Algorithm (GA)

Genetic Algorithm (GA) mimics the evolution of nature:



物竟天擇
適者生存

Crossover: children inherit genetic codes from parents

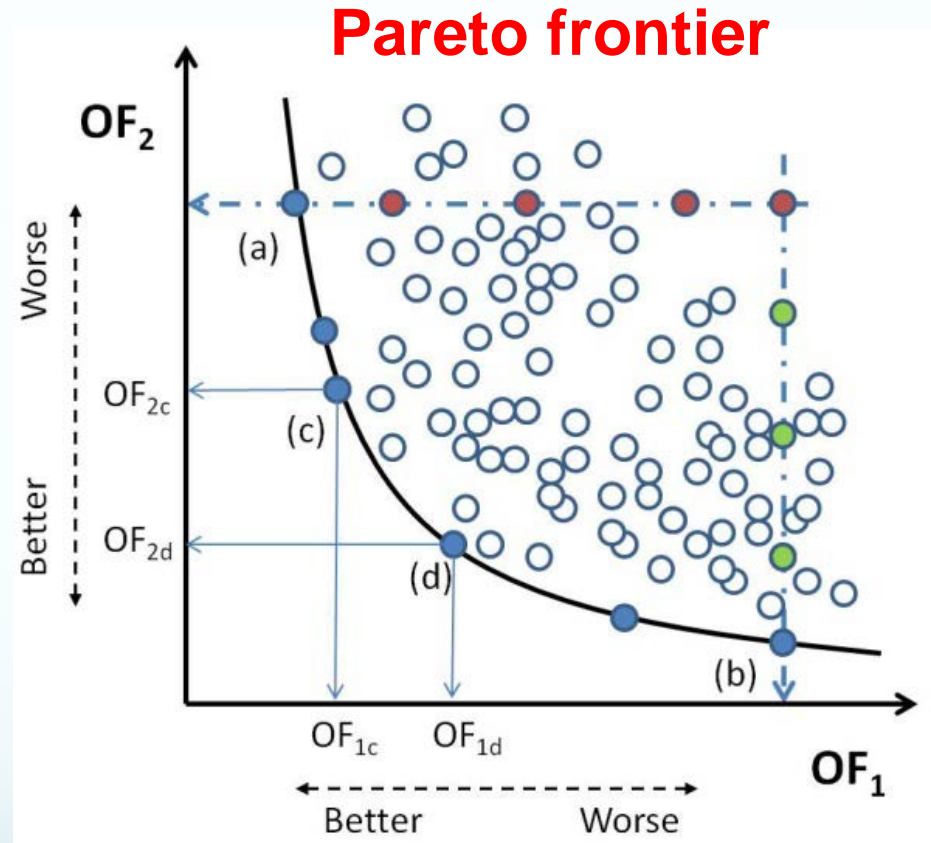
Mutation: *change* the children's genetic information

Selection: only these "*elites*" survive and reproduce

Multi-Objective Optimization

An example for two objectives ranking

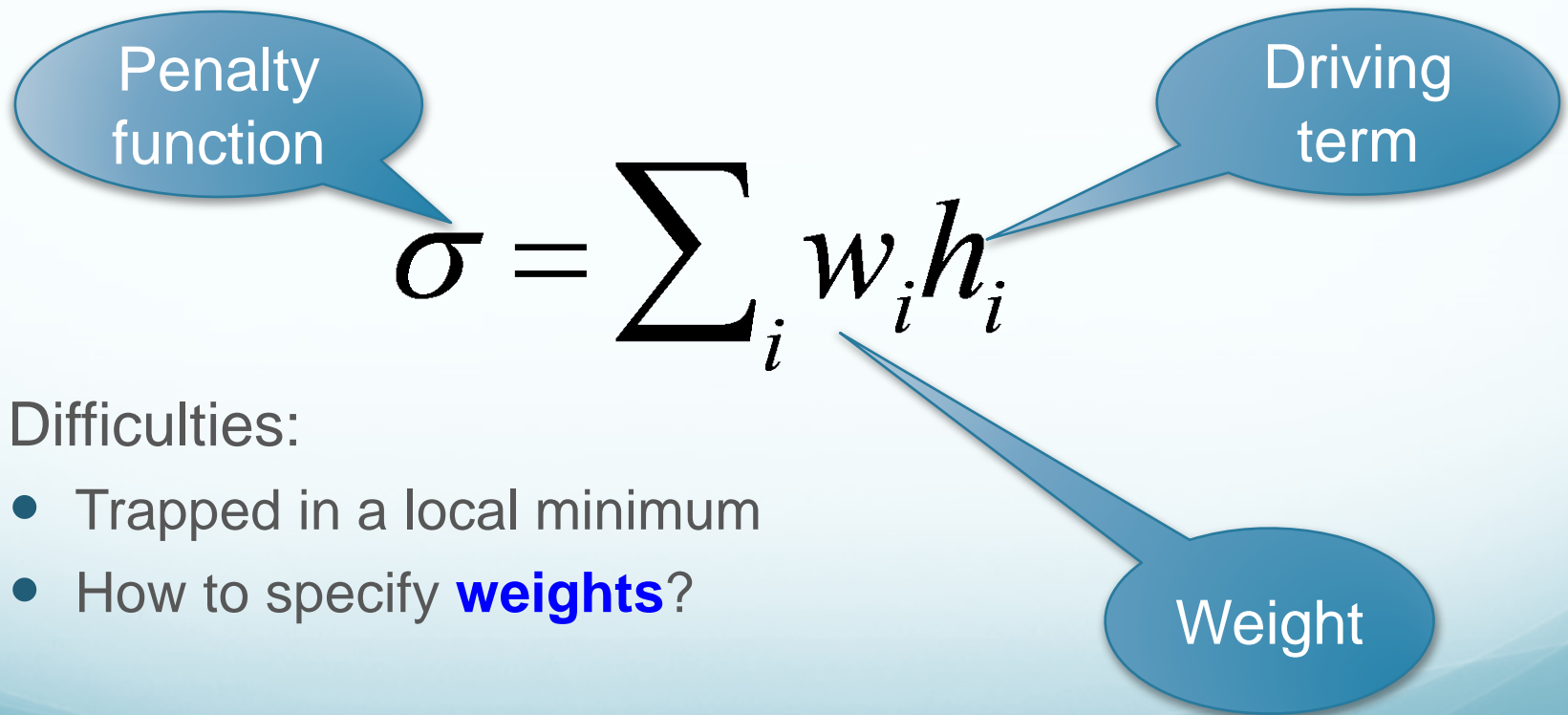
Within a same rank, all candidates are **equally good**



Deb, Kalyanmoy - Natural selection: Non-dominated sorting in N-dimension space

Review of existing methods

- Method 1: minimizing the nonlinear driving terms with specific weights, i.e. MAD

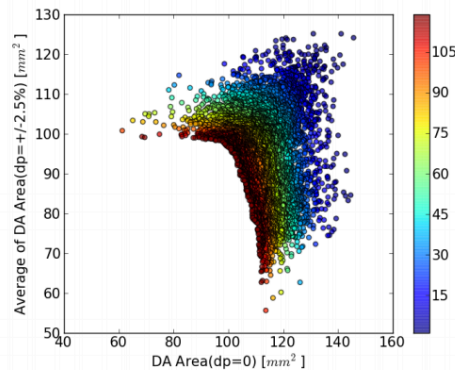
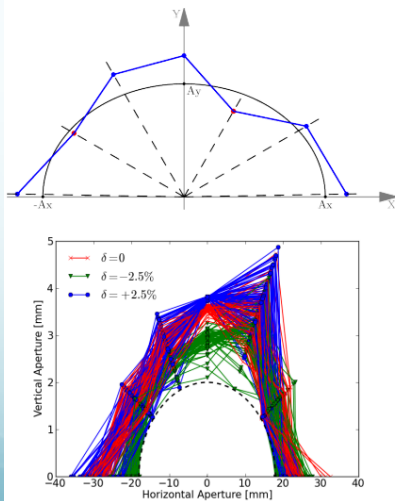


- Difficulties:
 - Trapped in a local minimum
 - How to specify **weights**?

Review of existing methods

- Method 2: brute-force MOGA driven by direct tracking
 - L. Yang, Y. Li, et al. (PRST-AB, 2011)
 - M. Borland, integrated to ELEGANT

Optimizing DA Area



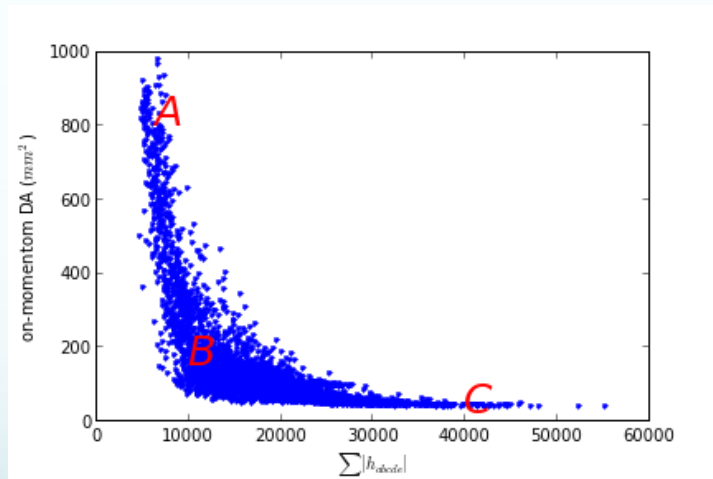
- 1 Objective func. are DA areas.
- 2 Constraints are fixed ellipse
- 3 Variables are 6 geom. sext.

Works very successfully, but,
Difficulties:

- No physics is behind
- Very time-consuming in direct DA tracking, especially when your computer is not powerful, or **your ring is big.**

Motivation

- A strong correlation between DA and NDTs does exist .(L. Yang & Y. Li @BNL, M. Borland & L. Wang @ANL and SLAC)



Correlation of NDT and DA
Yang and Li, PRST-AB

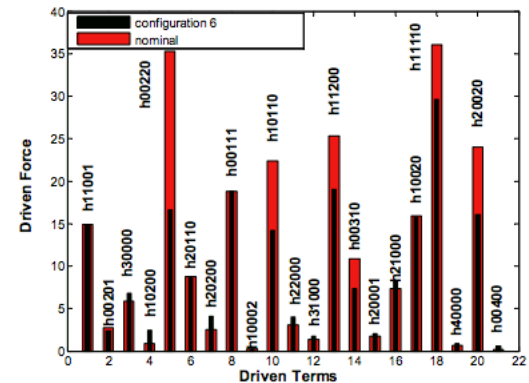


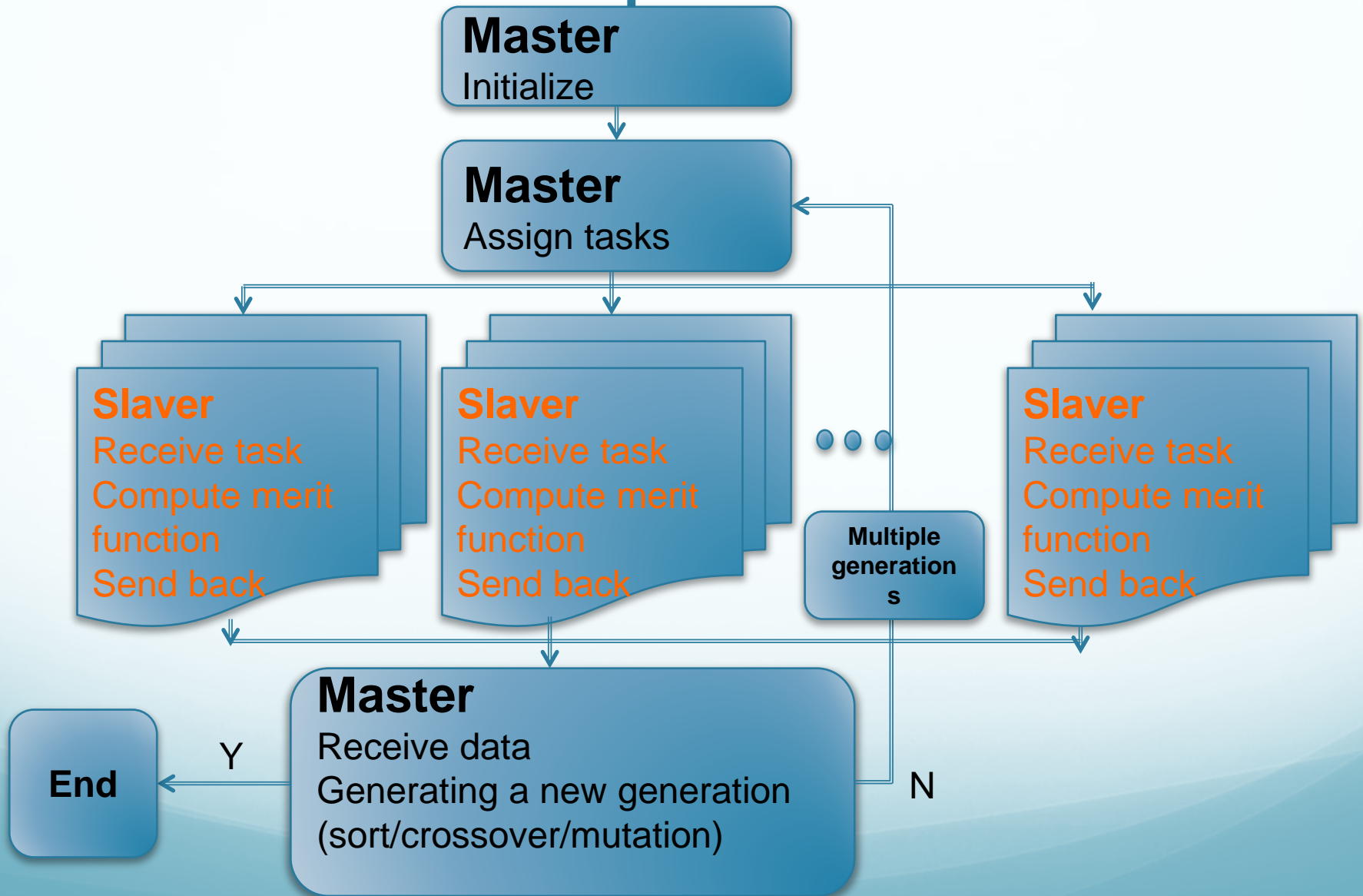
Figure 3. Automatic reduction of the driving terms after the optimization although DA is set as one of the objectives during the optimization.

M. Borland & L. Wang

An efficient method

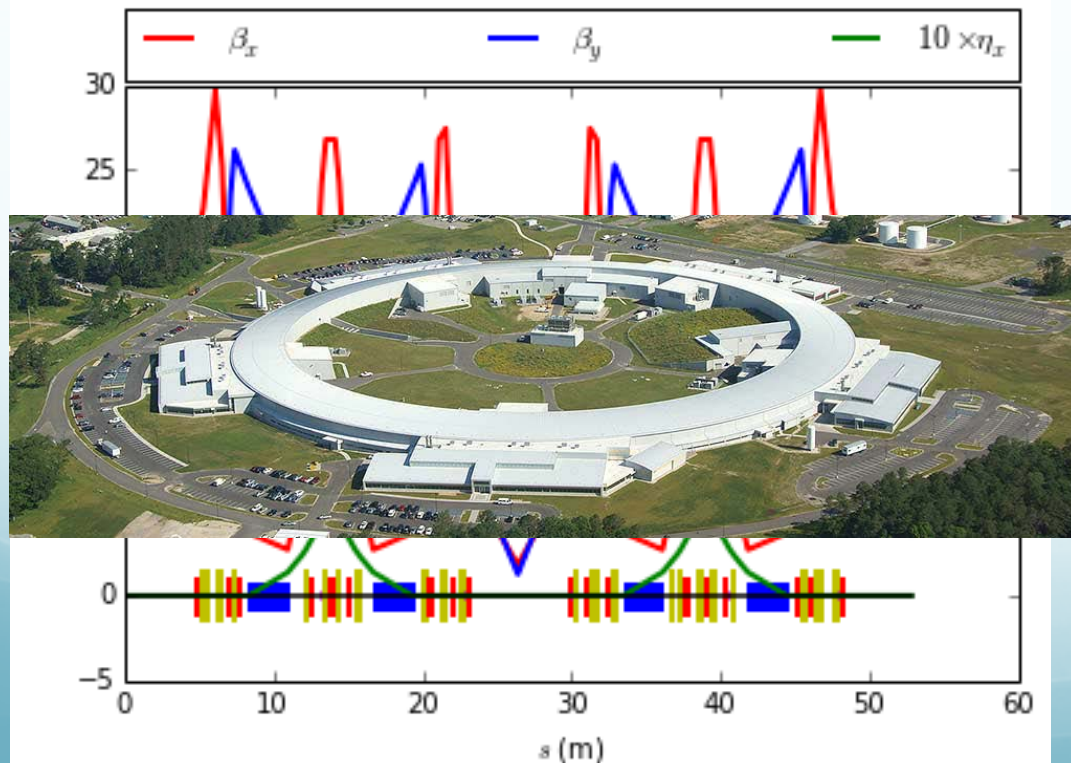
- **Using MOGA driven by NDT computing rather than DA tracking**
 - Be efficient: computing NDTs is much cheaper than DA tracking
 - Be of “physics”: having small low order NDTs is an **necessary** condition for larger DA

Parallel Computation and GA



Applications on NSLS-II ring

- Energy: 3GeV
- Emittance: 2nm bare, 1nm with 3x6.8m DWs
- Lattice: 30-standard DBAs (Chasman-Green)



Requirements for DA:

DA $\geq 15\text{mm}$ at high-beta straight for efficient injection

Energy acceptance $>2.5\%$ for sufficient beam lifetime

Tolerate numerous insertion devices and engineering errors

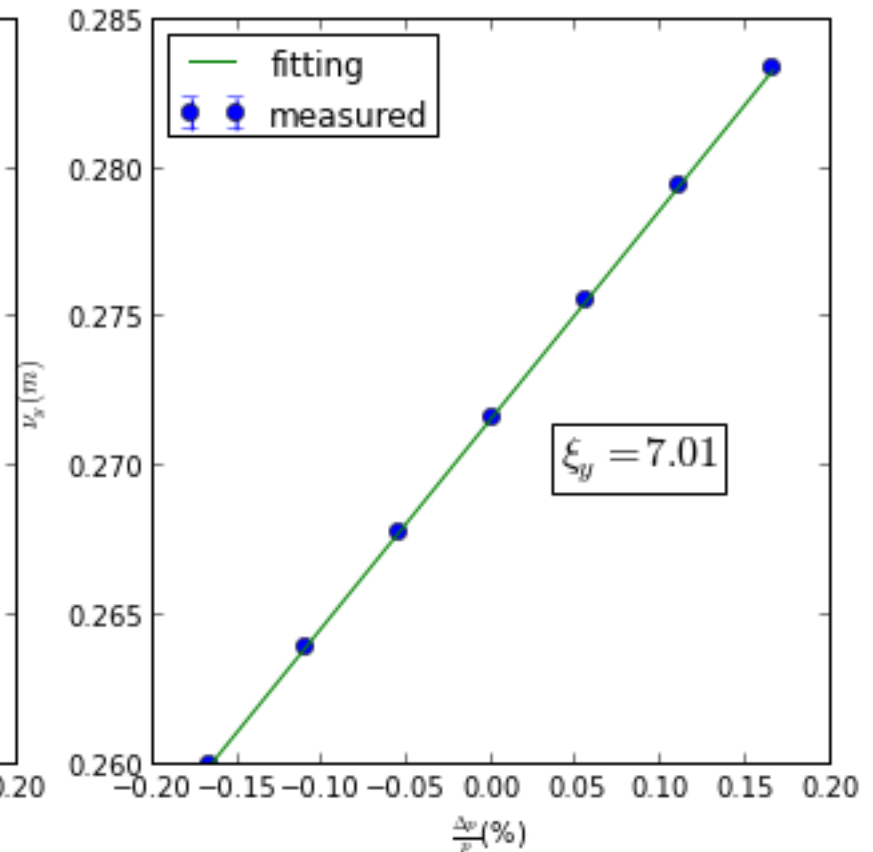
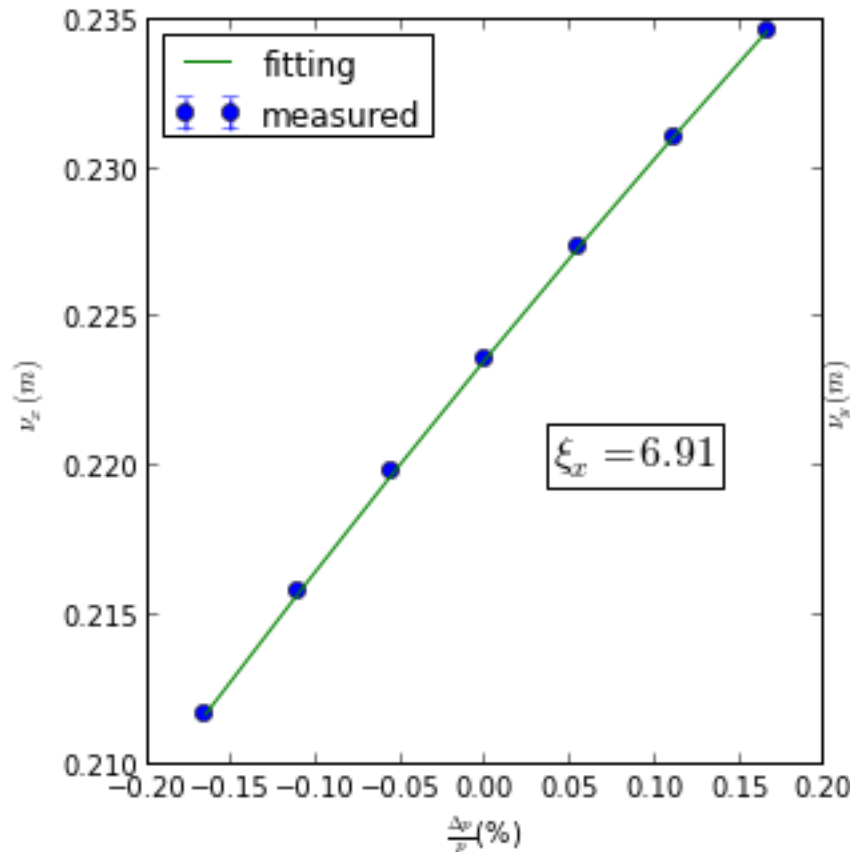
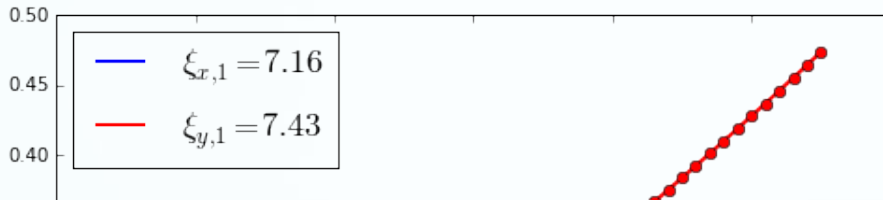
Simply case: Chromaticity

+7/+7

- Purpose: high linear chromaticity to stabilize beam at high stored beam current
- Optimization procedure:
 - Tuning chromatic sextupoles to achieve +7/+7 linear chromaticity
 - Tuning 6 families geometrical sextupoles to optimize DA and energy acceptance
 - Penalty functions: first and second order driving terms: $h_{abcd,e}$, where $a+b+c+d+e = 3$ and 4 (totally ~ 30 terms)

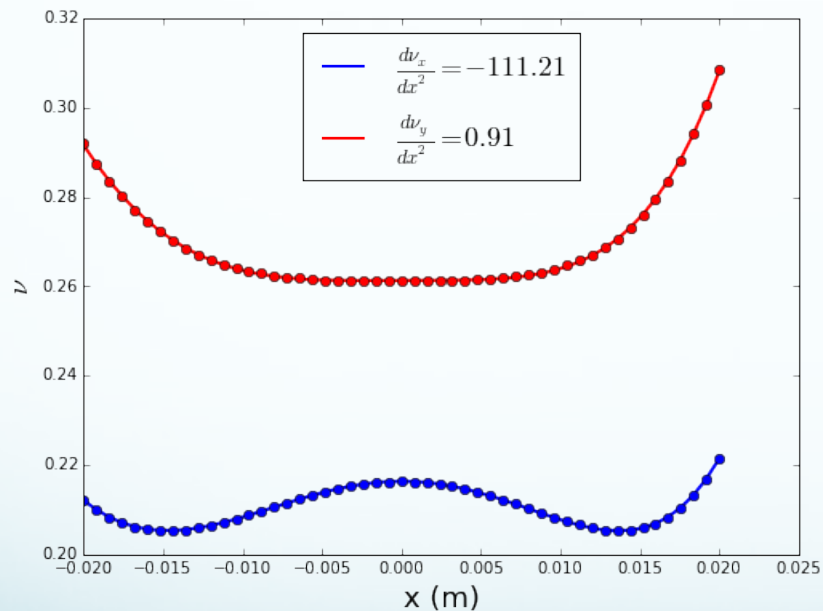
$\xi_{x,y} = +7/+7$ Dynamics: chromaticity

1. Linear chromaticity

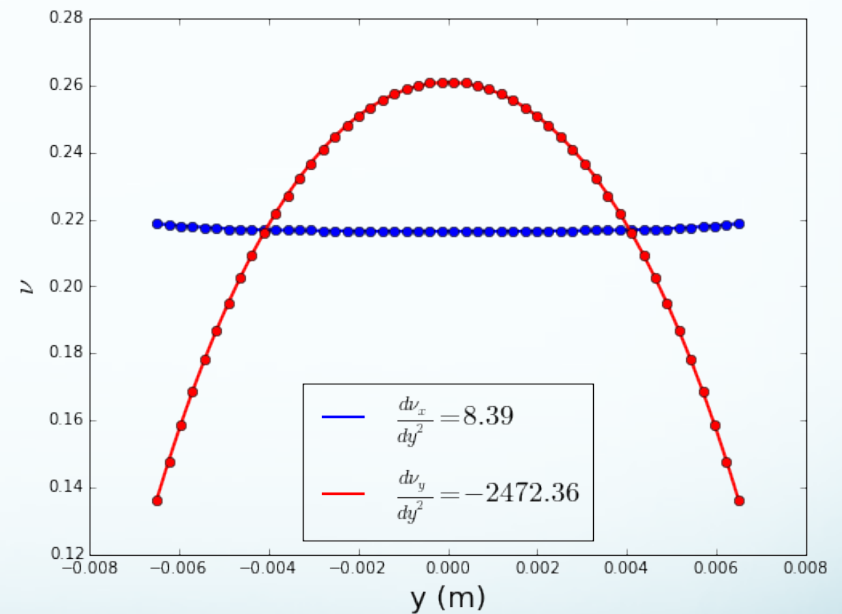


Tune dependence on amplitudes

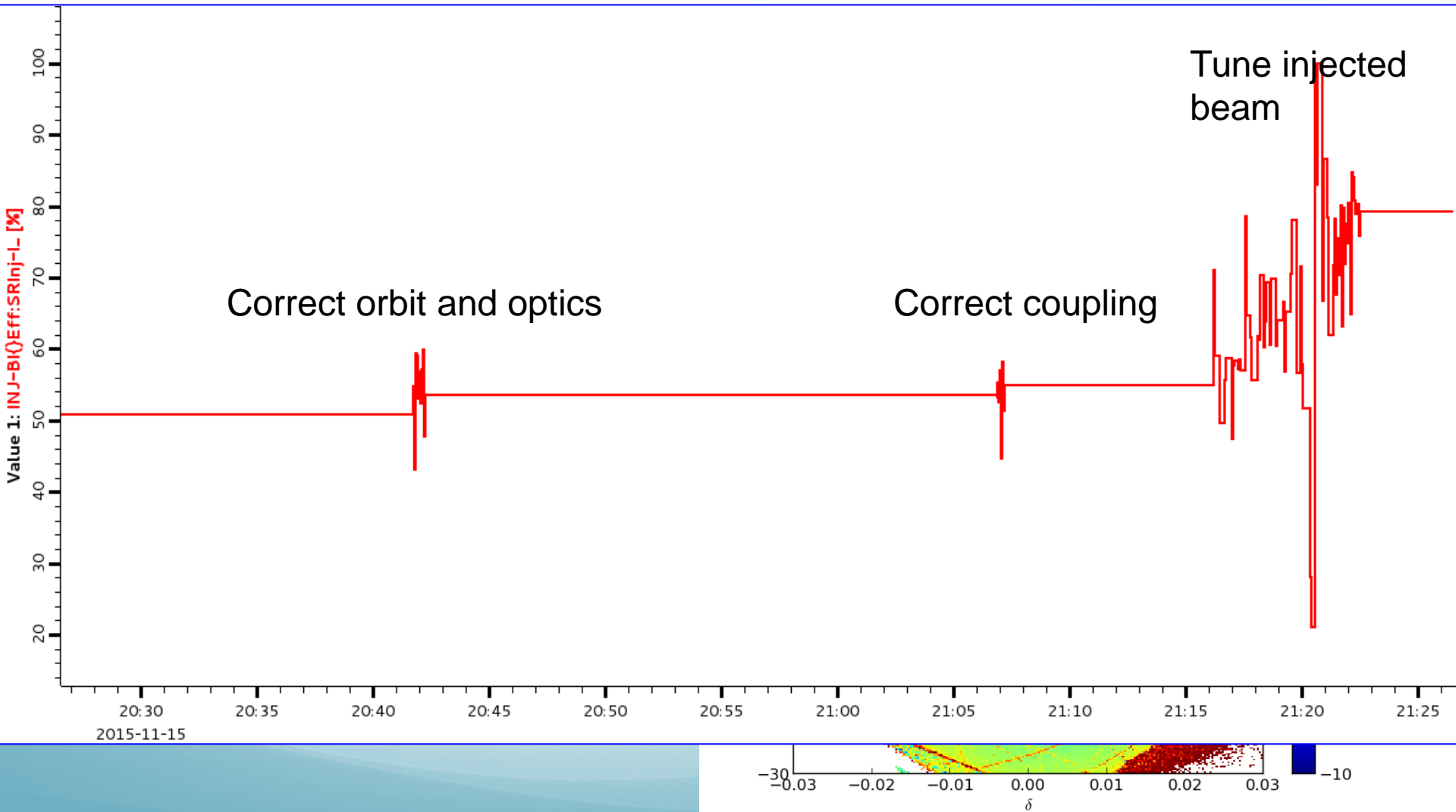
Horizontal



Vertical



Dynamic aperture and energy acceptance



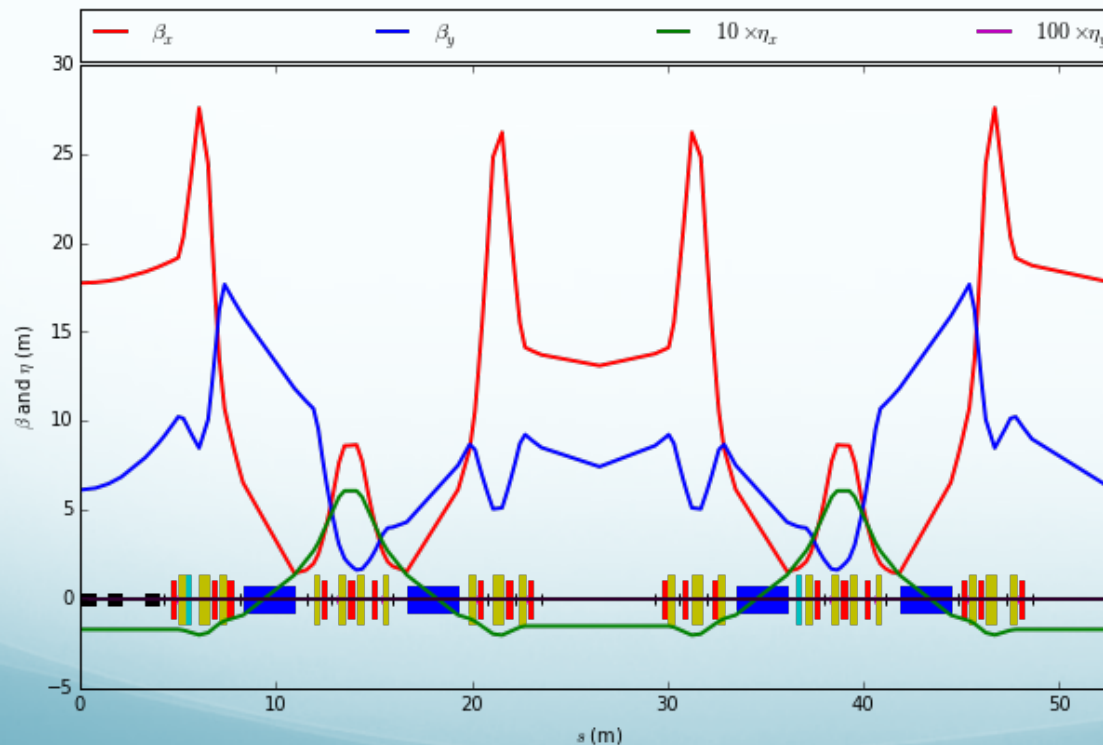
Demanding case: Low alpha Lattice

Purpose: to short bunch length by reducing momentum compactor from **$5e-4$** to **$3.4e-06$**

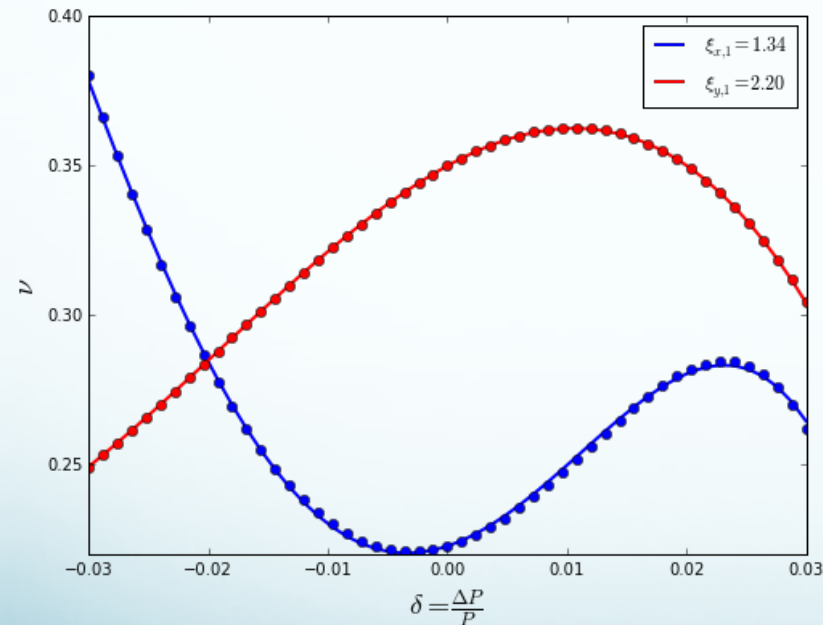
1. Linear chromaticity to +2/+2

2. Minimize higher order momentum compactions to have a stable longitudinal motion

3. Have sufficient DA and energy acceptance



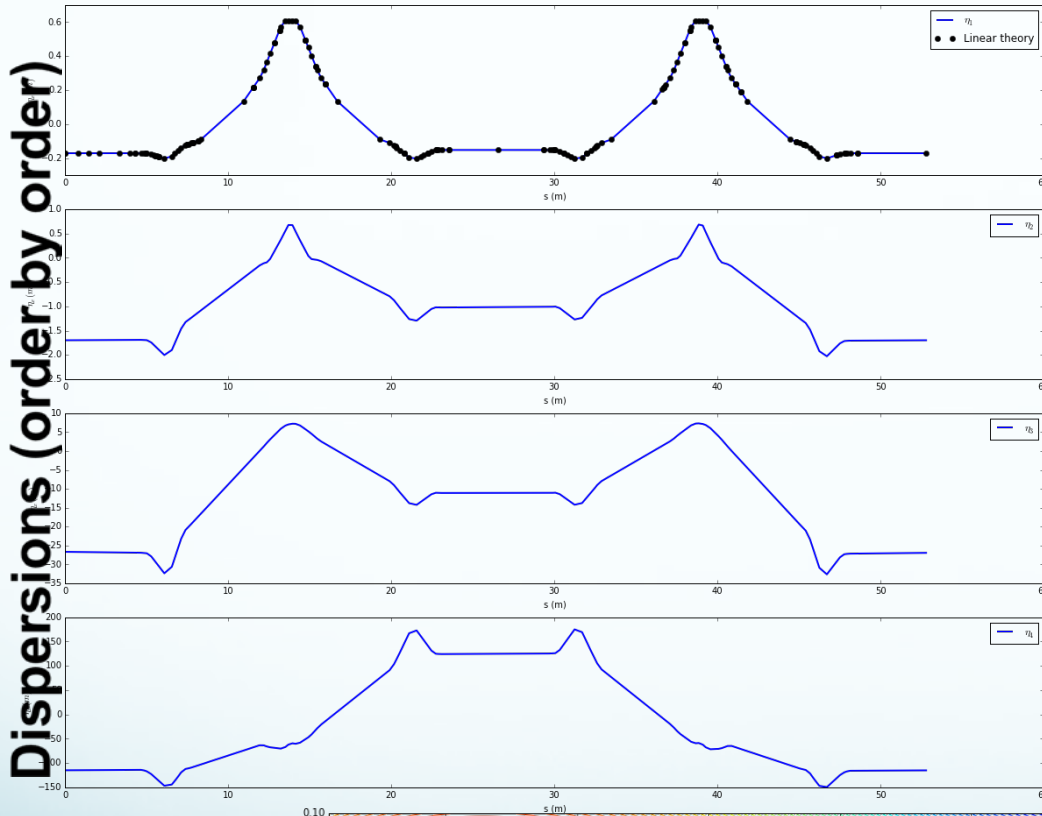
Objective 1: chromaticity control



1. linear chromaticity close to +2/+2
2. Large high-order chromaticities

Objective 2: longitudinal stability

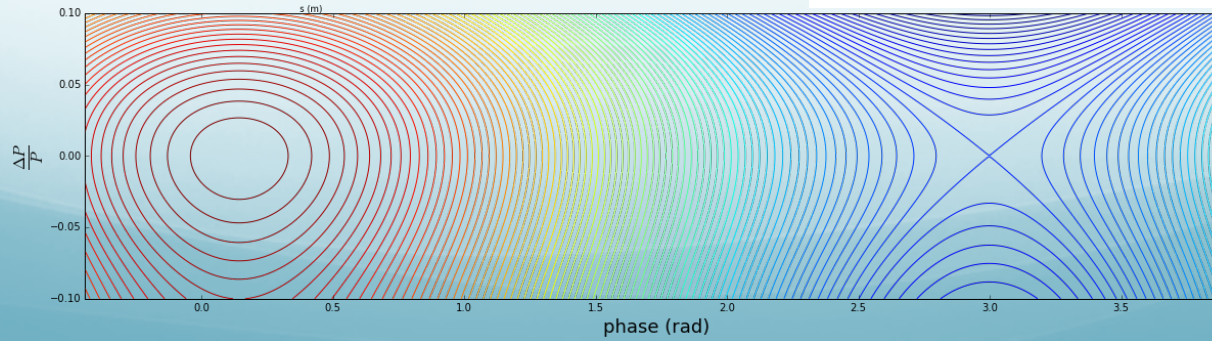
minimize higher order momentum compaction factors to have stable longitudinal motion



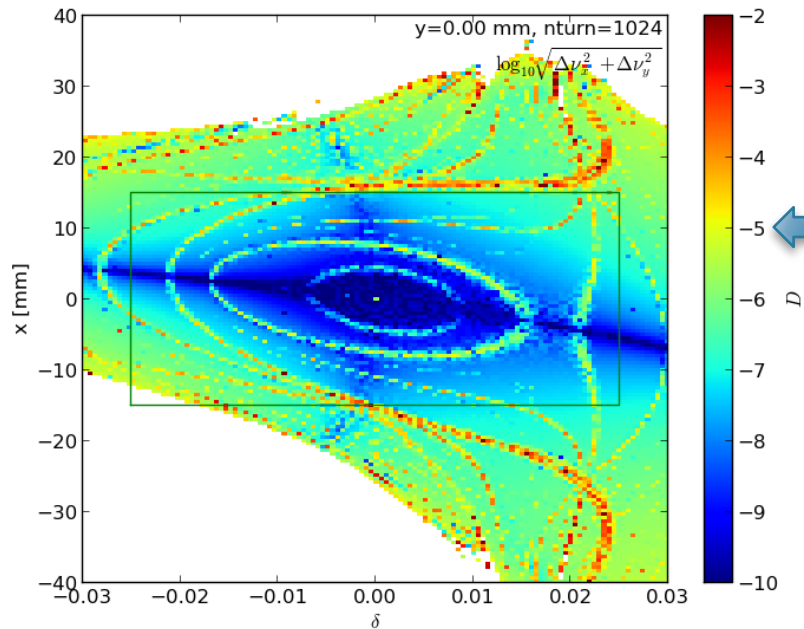
$$\alpha_1 = \frac{1}{\ell_0} \oint \frac{\eta_1(s)}{\rho} ds$$

$$\alpha_2 = \frac{1}{\ell_0} \int \frac{\eta_1'(s)^2}{2} + \frac{\eta_2(s)}{\rho} ds$$

$$\alpha_3 = \frac{1}{\ell_0} \int \eta_1'(s)\eta_2'(s) - \frac{\eta_1(s)\eta_1'(s)^2}{2\rho} + \frac{\eta_3(s)}{\rho} ds.$$

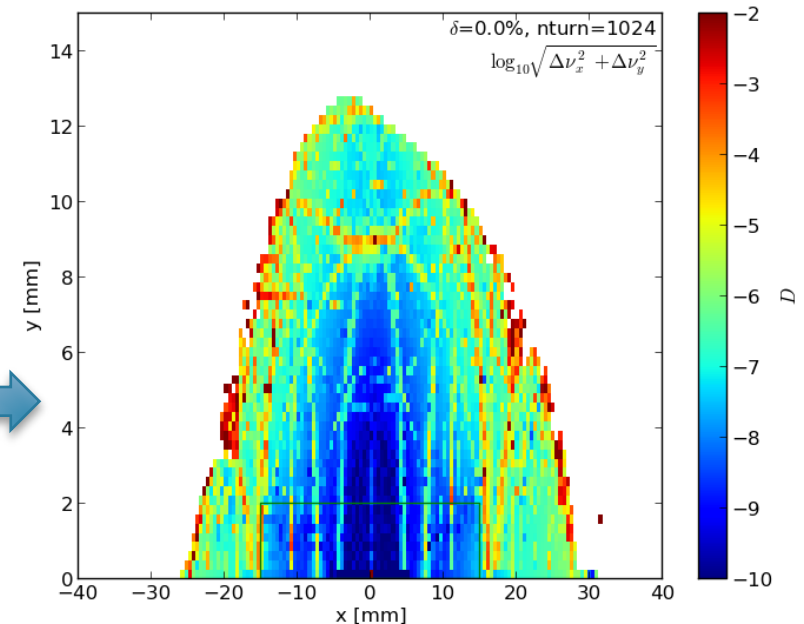


Objective 3: dynamic aperture and energy acceptance

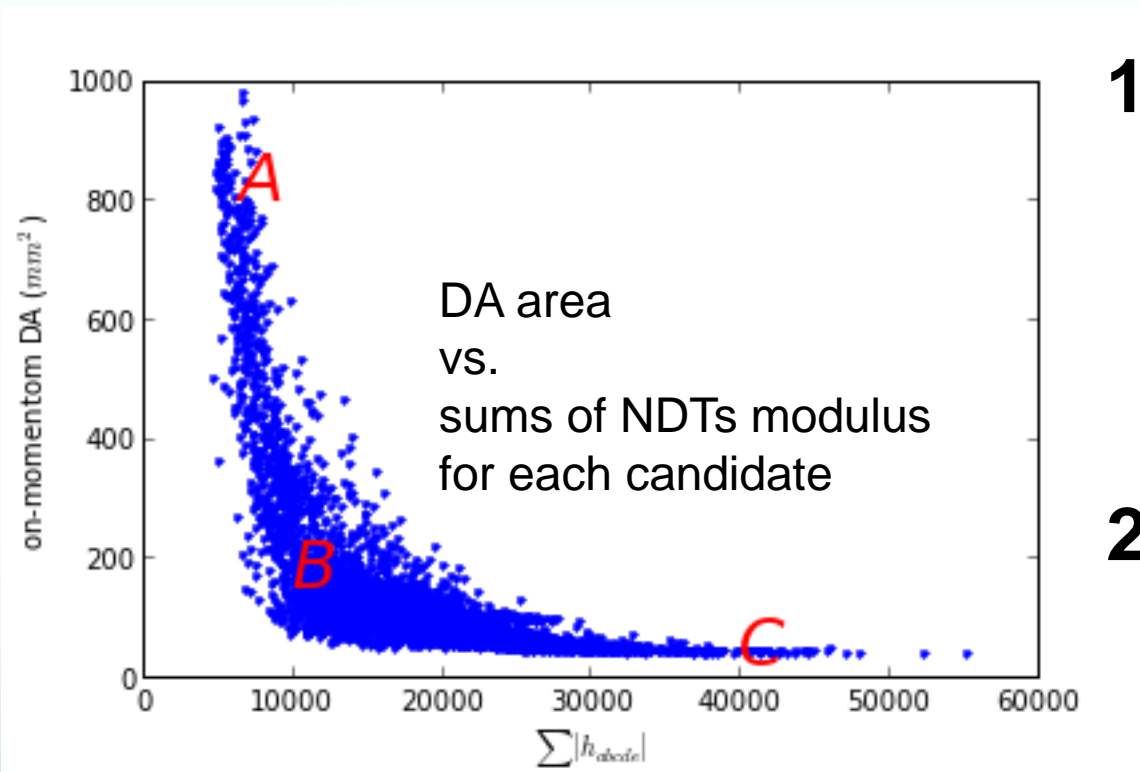


Sufficient energy acceptance for lifetime

Sufficient dynamic aperture for injection



Correlation between DAs and NDTs



A: small NDTs and large DAs

B: small NDTs but small DAs

C: large NDTs and small DAs

1. Having small NDTs is an **necessary** but **insufficient** condition for having a large DA
2. Sufficient population per generation is the key parameter to get some good solutions

New characterization with square matrix and sufficient conditions

We may now write this in the form

$$X = MX_0 \quad (2)$$

where to 4th order, we define the 14×1 monomial array

$$\tilde{X}_0 = (x_0 \quad p_0 \quad x_0^2 \quad x_0 p_0 \quad p_0^2 \quad \dots \quad p_0^4) \quad (3)$$

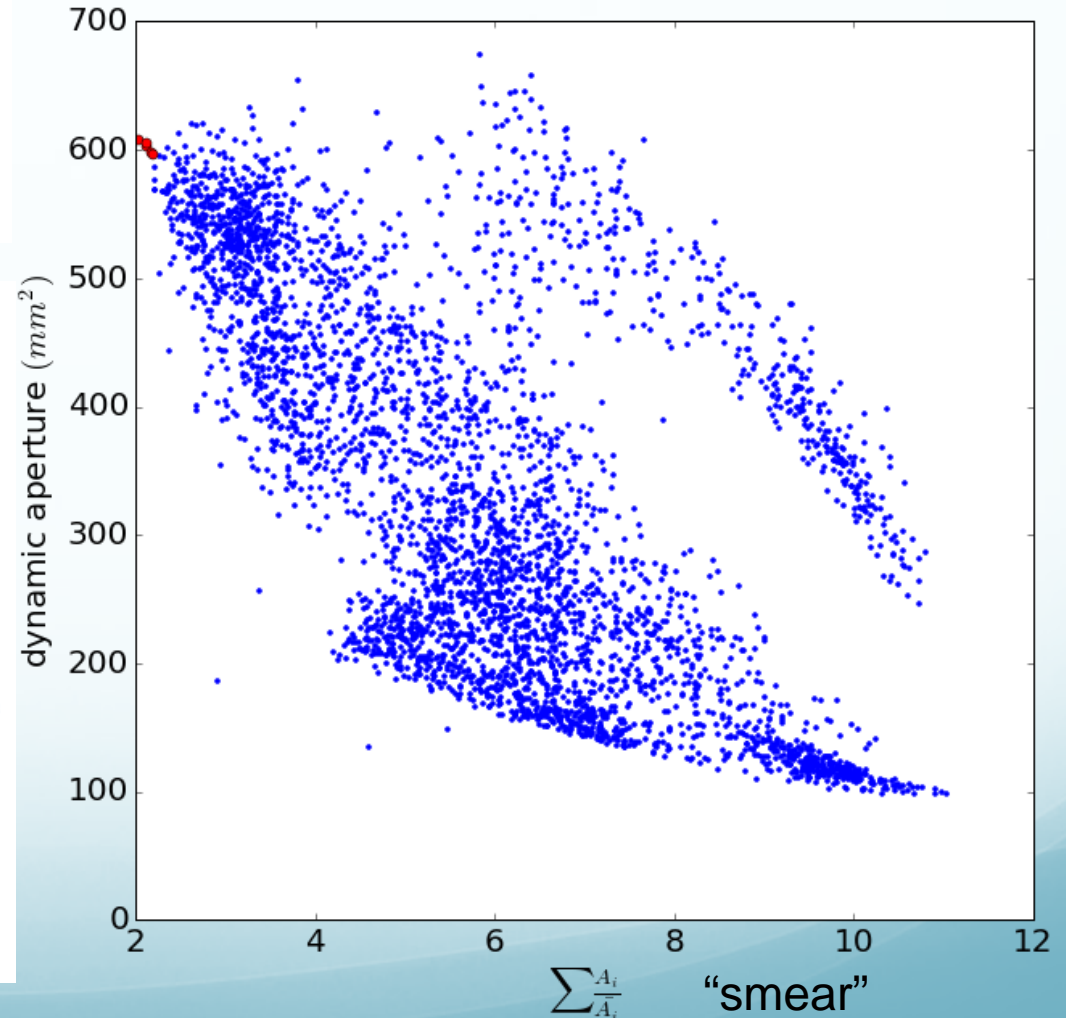
$$\tilde{N} = U\tilde{M}U^{-1} \quad (4)$$

$$= \begin{pmatrix} \tilde{N}_0 & & & & \\ & \tilde{N}_1 & & & \\ & & \tilde{N}_{-1} & & \\ & & & \tilde{N}_2 & \\ & & & & \tilde{N}_{-2} & \\ & & & & & \dots \end{pmatrix} \quad (5)$$

$$\tilde{N}_k = e^{ik\mu} I + \tau^\dagger \quad (6)$$

with $k = \pm 1, \pm 2, \dots$ I is the identity matrix and τ^\dagger the matrix with 1's just above the diagonal:

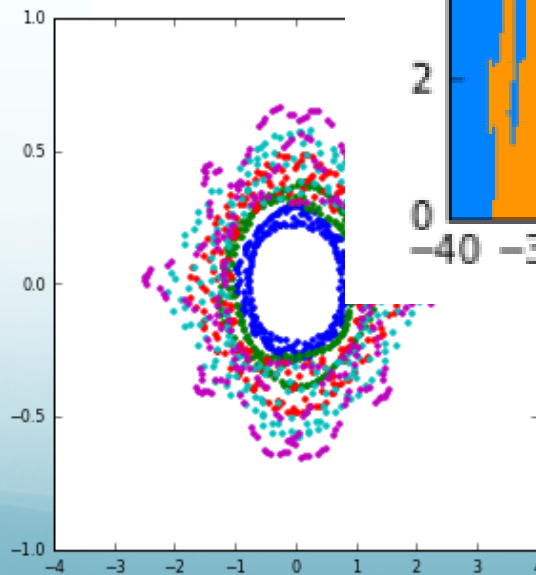
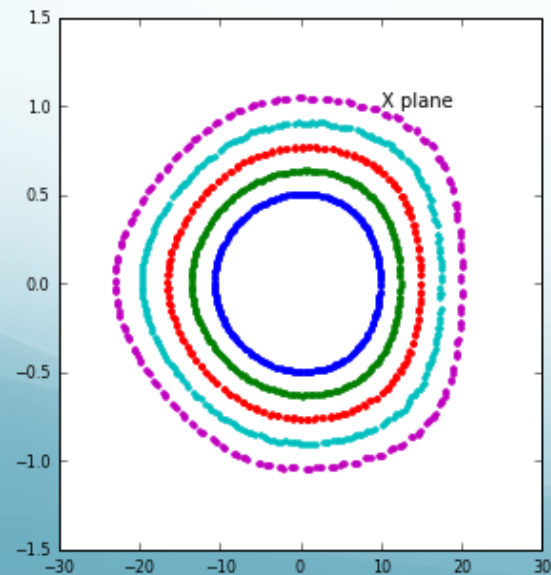
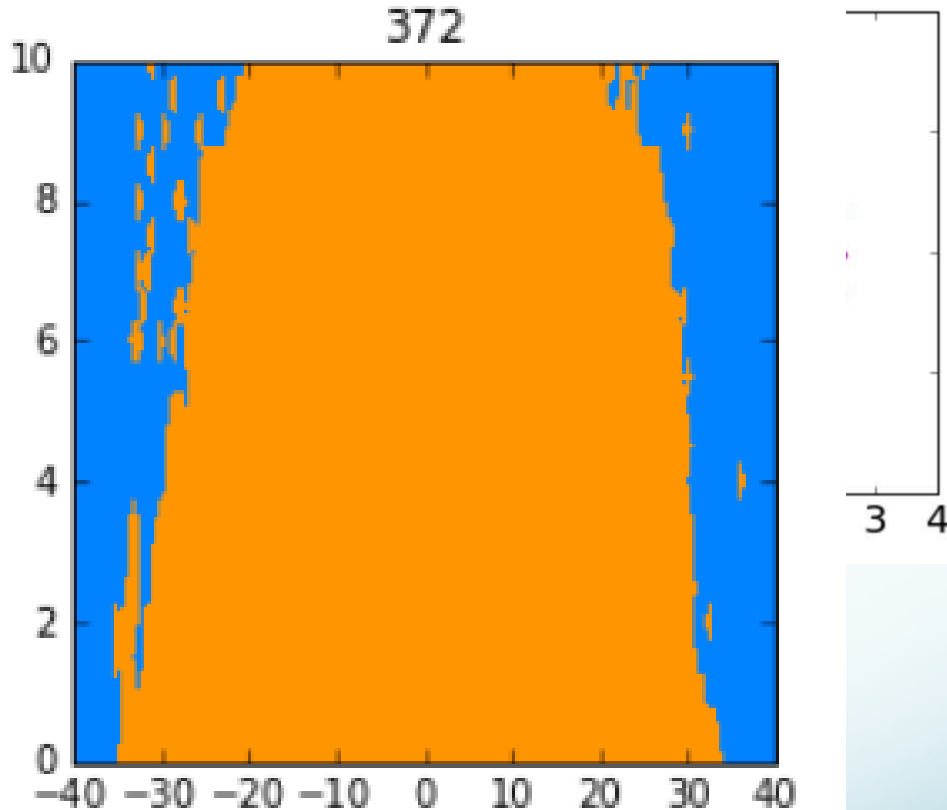
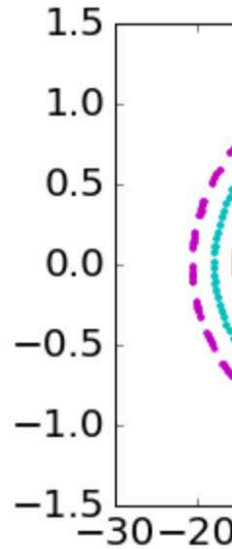
$$\tau^\dagger = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \tau = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \quad (7)$$



Phase space trajectories

Square matrix

Revisit $\xi = +7/+7$



Driving terms

Summary

- MOGA driven by the nonlinear driving terms is very **efficient**
- Having small low order NDTs is an **necessary**, but **insufficient** condition for have a decent DA.
- The number of populations is the key parameter. **Parallel** computation capability is preferable.
- Tracking simulation is the final criteria to select the best solutions from the last generation
- New approach of characterization of nonlinear dynamics is under development